DEEP REINFORCEMENT LEARNING FOR URLLC DATA MANAGEMENT ON TOP OF SCHEDULED EMBB TRAFFIC

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UNIVERSITÀ DI SIENA 1240

1 INTRODUCTION

- 2 Model
- 3 DEEP REINFORCEMENT LEARNING
- 4 RESULTS
- 5 CONCLUSIONS



- Finding a solution for the RAN slicing of eMBB and URLLC traffics;
- $\circ~$ The solution should exploit the dynamic nature of URLLC traffic.

WHY REINFORCEMENT LEARNING?

- Performing slicing of different type of traffic is a hard task;
- RL is able to find very good policies for systems that dynamically change through time;
- $\circ\,$ differently from other machine learning techniques, RL does not require collected data for training.

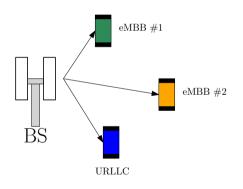


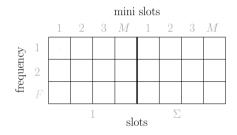
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Scenario & Resources

We consider a downlink transmission for single cell scenario with two set of users: eMBB and URLLC users.





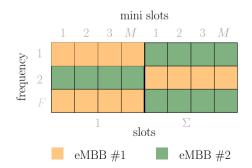
- $\circ~F$ frequency resources;
- $\circ~$ time resources are divided in Σ time slots;
- $\circ~$ each time slot is divided in M mini slots.



ENHANCED MOBILE BROADBAND (EMBB)

Specifications:

- high throughput;
- no latency requirement;
- resource allocation is made on a *time slot* basis;
- $\circ\,$ perfect knowledge of channel state information (CSI) at the BS.



eMBB resource allocation can be performed following conventional methods (e.g.water-filling, wMMSE, etc.)



ULTRA RELIABLE LOW-LATENCY COMMUNICATION (URLLC)

Specifications:

- low outage probability ($\leq 10^{-5}$);
- $\circ\,$ stringent latency requirement (≤ 1 ms);
- $\circ\,$ resource allocation is made on a $\min i \, slot \, {\rm basis}$

IN OUR SETTING, EACH PACKET:

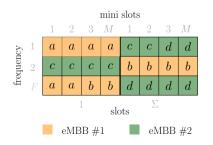
- has length equal to a mini slot;
- is generated in each mini slot following a Bernoulli with probability p_u ;
- $\circ~$ has a strict latency requirement $l_u^{\max};$
- $\circ\,$ is stored in a in FIFO queue ${\cal Q}$ of infinite length;



URLLC AND EMBB COEXISTENCE

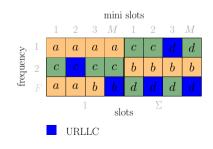
EMBB CODEWORDS:

- the BS distributes different codeword for each user;
- $\circ~$ codeword length is multiple of a mini slot;
- $\circ~$ each codeword is protected by a code able to recover D erased mini slots.



URLLC PUNCTURING:

- each URLLC packet is transmitted through puncturing selecting a time-freq resource;
- a transmitted URLLC packet is always *successfully decoded*.



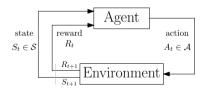
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RL IN A NUTSHELL

Reinforcement Learning

Reinforcement Learning is a field of Machine Learning studying the behaviour (policy) of a certain agent (model) acting in an environment (in which Markov property holds).



- The agent accumulates a discounted return $G_t = \sum_{k=0}^{\infty} \gamma^k R_{t+k+1}$ with $\gamma \in [0,1);$
- The probability distribution of G_t depends on the policy $\pi(a|s)$ that chooses the action a for each possible state s;

The objective of RL is to find a policy that maximizes the expected discounted return.



MODEL AS A MARKOV DECISION PROCESS

Each step t of the simulation is a mini slot of the allocation grid.

- Actions: $A_t = \{0, 1, \dots, F\}$, where 0 means no transmission, while otherwise the action indicates the FR index.
- State: $S_t = \{S_t^{(u)}, S_t^{(e)}\}$ where
 - $\mathcal{S}_{t}^{(u)} = \{Q_t, \Delta_t\}$
 - $S_t^{(e)} = \{s_t(f)\}_{f=1}^F$ tracking how much the eMBB codeword on (t, f) is protected.
- Reward: $R_t = \sum_{w \in \mathcal{W}_t} e_t(w) + L_t$

$$e_t(w) = \begin{cases} -1, & \text{if } \mathcal{A}_t \text{ causes the outage of } w, \\ 0, & \text{otherwise,} \end{cases} \quad L_t = \begin{cases} 0, & \Delta_t \ge 0, \\ -\frac{3T}{F+1}, & \Delta_t < 0. \end{cases}$$



PPO AND NN ARCHITECTURE

PROXIMAL POLICY OPTIMIZATION (PPO):

- aims to the biggest possible improvement step on a policy without ending too far from the starting point one, thus avoiding the risk of performance collapse;
- $\circ\,$ is an actor-critic algorithm \rightarrow two different neural networks are required.

NN ARCHITECTURE:

Two completely separated subnetworks:

- *value function*: three ReLU dense layers with 128, 64, and 32 neurons + fourth with single neuron to estimate the value with no activation;
- *policy function*: three ReLU dense layers with 128, 64, and 32 neurons + dense fourth layer with F + 1 neurons to choose the actions with *softmax* activation.



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SIMULATION PARAMETERS

- $\circ\,$ Resource grid: $F=12,\,10$ time slot, M=14 mini slot each $\rightarrow\,T=140;$
- Users: 1 URLLC user, 10 eMBB users;
- Maximum delay constraint to $l_u^{\max} = 7;$
- $\circ~$ Degree of protection of eMBB codewords: $D\in\{0,1\}.$

LEARNING PHASE

- the parameters related to eMMB resource allocation and URLLC traffic generation are randomized on an episode basis: random allocation, codeword placement, protection of each codeword, and probability of URLLC packet.
- $\circ~$ We initialize each episode with a random number of URLLC packets in the queue (always smaller than $l_u^{\max}).$



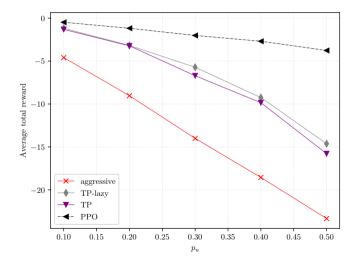
COMPARISON SCHEMES

- $\circ~Aggressive.$ The URLLC packet is transmitted immediately on a randomly chosen frequency.
- Threshold Proportional (TP). The URLLC packet is transmitted immediately on the frequency resource occupied by the codeword with the highest puncturing threshold¹.
- *TP-lazy.* As long as $\Delta_t > 0$, the packet is transmitted only if the present state is somehow better (or equal) than the next one. If $\Delta_t = 0$, the transmission is forced in the present mini slot. In any case, the choice of the frequency is made according to the TP scheme.

¹A. Anand, G. de Veciana, and S. Shakkottai. "Joint Scheduling of URLLC and eMBB Traffic in 5G Wireless 15/24 Networks". In: *IEEE/ACM Transactions on Networking* 28.2 (2020), pp. 477–490.



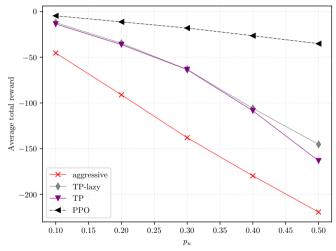
Average total reward, T = 140





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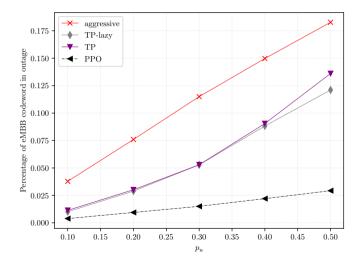
Average total reward, T = 1400



The same NN trained for T=140 is used here, proving the generalization capacity of the agent. $^{17/24}$



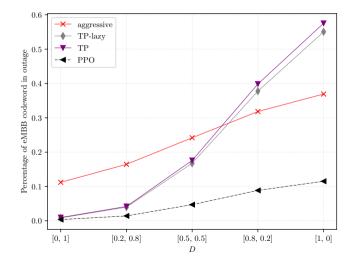
EMBB codeword in outage vs p_u , T = 1400





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EMBB CODEWORD IN OUTAGE VS DEGREE OF PROTECTION





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CONCLUSIONS

- We proposed a Deep Reinforcement Learning approach to the slicing task with respect to eMBB and URLLC traffic;
- Our agent learns from scratch a policy outperforming all the man-made schemes over multiple performance metrics;
- The agent's learned policy is agnostic to the length of each episode allowing for fast self-training while still being applicable to the real world task.



FUTURE WORKS

- Taking into account the reliability of the URLLC user;
- Adopting a Poissonian distribution to better simulate the generation of URLLC packets;
- $\circ~$ the agent should be able to transmit more than one packet over multiple frequencies;
- $\circ\,$ Enabling the Power Domain Non-Orthogonal Multiple Access (NOMA) communication.



BIBLIOGRAPHY & RESOURCES

- **Paper**: Fabio Saggese, Luca Pasqualini, Marco Moretti, and Andrea Abrardo. Deep Reinforcement Learning for URLLC data management on top of scheduled eMBB traffic. 2021. arXiv: 2103.01801 [eess.SP]
- o Github: https://github.com/InsaneMonster/teler12021
- o Framework: https://github.com/InsaneMonster/USienaRL



Thank you for the attention.



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